Power Electronics

Function Diagram

T1/T2/T3

X1/X2

11-14 11-12

M Mot

MINISTART Softstarter For Heating Pumps PF 9029

Translation of the original instructions





Your Advantages

- For starting current limitation in heat pumps to provide stable mains conditions
- Only one small device 67.5 mm for
- softstart, motor protection, voltage- and phase sequence monitoring
- Soft start and minimized staring current
- Extended service life of AC motors and mechanical drive system
- Motor power up to 18.5 kW
- Short ramp up time 25 A: < 200 ms
- 36 A: < 300 ms
- · Energy saving by bridging of the semiconductors after softstart
- Symmetrical staring current

Features

Motor voltage

LED yellow

LED green

Failure e.g. undervoltage

- According to IEC/EN 60947-4-2
- 3-phase controlled with integrated bypass relays
- Phase sequence monitoring
- Undervoltage monitoring
- Overvoltage monitoring
- · Blocked motor monitoring in bypass mode
- Integrated motor protection to class 10 acc. to IEC/EN 60947-4-2
- Starting current limitation
- · Thyristor monitoring
- · Detection of missing load
- Automatic frequency detection of supply voltage
- Temperature monitoring of power semiconductors

Approvals and Markings



Applications

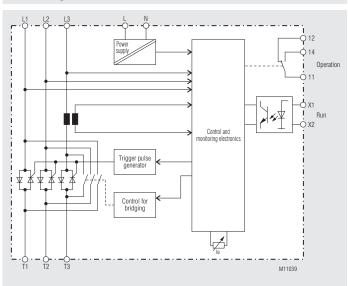
• Softstarter for compressor motors

Product Description

The PF 9029 from the MINISTART-family is a robust electronic control unit for soft starting of compressor motors with integrated monitoring functions. After successful starting the semicon-ductors are bridged by relays to minimize the power dissipation of the units.

Block Diagram

Starting time



Function Notes

Variation of speed is not possible with this device.

Device Description

Failure Mode

The softstarter is monitoring different parameters. If failure is detected the unit switches off. In failure mode a red LED with flash code signals the fault. The failure mode can be reset by pressing the reset button or by disconnecting the power supply.

Undervoltage monitoring

To make sure the motor is operated with the correct voltage the voltage is monitored. The voltage is not monitored in ramp up mode. If the voltage drops below 330 V for longer than 1 s the unit switches to failure mode.

Overvoltage detection

To make sure the motor is operated with the correct voltage the voltage is monitored. The voltage is not monitored in ramp up mode. If the voltage rises above 470 V for longer than 1 s the unit switches to failure mode.

Phase sequence monitoring

The phase sequence monitoring function monitors clockwise phase sequence of the 3-phase system. An anti-clockwise sequence forces the unit to failure mode.

Shortcircuited Thyristor

Before each softstart the power-semiconductors are tested for short circuit A detected short circuit forces the unit to failure mode. For short circuit test the motor must be connected.

Motor not connected

Before each softstart it is tested that the motor is correctly connected to the unit. This test avoids that the motor starts on 2 phases and gets faulty. Wrong connection forces the unit to failure mode.

Overtemperature

The temperature of the semiconductors is measured by NTC sensor. Overtemperature forces the unit into failure mode.

Frequency detection

To achieve a correct function the actual frequency has to be known. The frequency is monitored after power on or reset. If the frequency is outside the limits $50\text{Hz} \pm 5 \text{ Hz}$ or $60 \text{ Hz} \pm 5 \text{ Hz}$ the unit switches to failure mode.

Blocking protection

In Bypass mode a blocking of the motor is detected by current monitoring. If the current exceeds 4 times the nominal current of the motor, the unit recognizes motor blocking. The unit switches to failure mode.

Overload protection

The unit incorporates an electronic overload protection, which is realized by monitoring the current in one phase. Overload protection class 10 is a fix setting. The response current can be adjusted with a potentiometer by adjusting the motor rated current. When the I2t value is overridden the unit switches into failure mode. The I²t value is reset with the reset function.



Note: At loss of the auxiliary supply the actual I²t -value is stored. At restart the I²t -value is recalled and used for operation independent how long the motor was cooling down.

Limitation of starting current

By starting current limitation the peak current can be limited. The load on the supply network is lower. The time limit of the current is monitored and if the starting time exceeds the limit of 5 s a failure signal is indicated. The current limit is fixed to 2.5 times the motor nominal current.

Indication

The device status is indicated with different coloured LEDs and flash code

LED green: Device ready

LED yellow: On, when bridging relay active

LED red: Flashes if error (see flash codes)

Control Elements

Potentiometer I :: Nominal current for overload protection

and starting current limitation.



Note:

The potentiometer setting is only read when connecting the power supply or on reset at failure mode.

Reset-button: Reset of failure mode after failure is removed

and confirming potentiometer setting.

Control Circuit

The control input works with a voltage of AC/DC 20 ... 300 V.



After reset or disconnecting the power supply the unit initiates a softstart, if voltage is connected to control input.

Outputs

One output relay is available.

The monitoring contact "operation" closes when the start signal is connected. It opens after the signal is disconnected or when an error occurs.

Auxiliary Supply

To monitor phase failure on all 3 phases an external auxiliary supply of AC 230 V is necessary.

Fault Indication by Flashing Code

During normal operation failure messages may occur. The messages are indicated by a flashing sequence of the red LED0

Flashes *)	Fault	Possible cause	Troubleshooting
1 x fast	Motor voltage is missing	Defective fuse, faulty wiring	Check fuses and wiring
1	Device temperature to high	Duty cycle exceeded	Reduce operating time, use heat sink if possible
2	Mains frequency out of tolerance	Wrong frequency	Device is not suitable for actual frequency. Contact manufacturer
3	Phase sequence incorrect	Load voltage incorrect. Clockwise phase sequence is mandatory for correct function	Check wiring, change 2 phases
4	Undervoltage detected	Load voltage under 330V	Check load voltage
5	Overload detected	Motor overloaded	Reduce operating time, Motor rough-running? Adjust nominal current
6	Motor blocked in Bypass-Mode	Motor stalled in operation	Check motor
7	Thyristor short-circuit	Faulty thyristor detected	Device has to be repaired
9	Motor connected incorrectly	One or more wires to the motor are interrupted	Check wiring to motor
10	Temperature sensor defective	Interruption or short circuit in temperature sensor of power semiconductors	Device has to be repaired

^{*)} No.: Number of flash pulses in a series

Technical Data

AC 230 V ± 10% Auxiliary supply: Overvoltage protection: Varistor AC 275 V Starting voltage: 3 AC 220 V

Ramp up time: 0.2 s $0.3 \, s$ Undervoltage protection: 3 AC 330 V, for more than 1s Overvoltage protection: 3 AC 470 V, for more than 1s

Resolution of

voltage measurement: AC 1.5 V Nominal consumption: 4 VA

Short circuit detection 5 ... 25 A 10 ... 36 A 50 A gG / gL Mode 1: 35 A gG / gL Mode 2: 5510 A²s 5500 A2s



Coordination Type!

Coordination type 1 according to IEC 60947-4-1: The engine control unit is defective following a short circuit and must be replaced.

Coordination type 2 according to IEC 60947-4-1: The engine control unit is still suitable for continued use following a short

Control Input

Control voltage: AC/DC 20 ... 300 V Control input current: 0.2 mA ... 3.1 mA Start up delay: 10 ... 50 ms Release delay: 200 ms

Indicator output

Contacts: 1 changeover contact

Switching capacity

to AC 15 NO contacts: NC contacts:

3 A / AC 230 V IEC/EN 60947-5-1 1 A / AC 230 V IEC/EN 60947-5-1 Electriscal life

2 x 105 switching cycles

Max. 1800 switching cycles / h

To AC 15 at 3 A. AC 230 V: Permissible switching

frequency:

Short circuit strength

Max. fuse rating: IEC/EN 60947-5-1 4 A gG/gL Mechanical life: ≥ 10⁸ switching cycle

Output / Load Circuit

Load circuit Nominal operating

voltage L1-L3: 3 AC 340 ... 460 V Peak reverse voltage: 1200 V

Overvoltage protection: Varistor 510 V

Nominal frequency: 50 Hz \pm 5 Hz or 60 Hz \pm 5Hz 25 A (AC-53b) Nominal operating current Ie: 36 A Setting range I_e: 5 A ... 25 A 10 A ... 36 A Stoßstrom: 1050 A (tp = 10 ms)

Load limit integral:

Resolution current

measurement: 0.1 A 0.2 A Usage category I_a: AC-53b: 2.5 - 0.5: 60 10

Number of starts per hour: Overload protection:

Blocking protection,

response value: 4 x I_e, for longer than 1 s in bypass mode **Current limiting:** $2.5 \times l_e \pm 10\%$ during ramp up

Class 10

5500 A²s

Technical Data

General Data

Temperature range

Operation: 0 + 50 °C

> At an altitude of > 1000 m the maximum permissible temperature reduces by

0.5 °C / 100 m

- 20 °C ... +75 °C Storage:

< 95%, no condensation at 40 °C Relative air humidity:

Altitude: < 2000 mClearance and Creepage distances

rated impulse voltage / pollution degree

. Mains-/Motor voltage-

heat sink: 6 kV / 2 IEC/EN 60947-4-2

Mains-/Motor voltage-

control voltage: 6 kV / 2 IEC/EN 60947-4-2

Mains-/Motor voltage-

indicator relay: 6 kV / 2 IEC/EN 60947-4-2 Overvoltage category: Ш

EMC

Interference resistance

Electrostatic discharge (ESD): 8 kV (air) IEC/EN 61000-4-2

HF-irradiation

80 MHz ... 1.0 GHz: 10 V / m IEC/EN 61000-4-3 1.0 GHz ... 2.5 GHz: 3 V / m IEC/EN 61000-4-3 2.5 GHz ... 2.7 GHz: 1 V / m IEC/EN 61000-4-3 Fast transients: 2 kV IEC/EN 61000-4-4

Surge voltage between

Wires for power supply: 1 kV IEC/EN 61000-4-5 Between wire and ground: 2 kV IEC/EN 61000-4-5 HF-wire guided: IEC/EN 61000-4-6 10 V IEC/EN 61000-4-11

Voltage dips: Interference emission

Limit value class B IEC/EN 60947-4-2 Wire guided: Radio irradiation: Limit value class B IEC/EN 60947-4-2 Harmonics in bypass mode: IEC/EN 61000-3-11

Degree of Protection

IP 40 IEC/EN 60529 Enclosure: IP 20 Terminals: IEC/EN 60529

Housing: Thermoplastic with V0 behaviour acc. to UL subject 94

Vibration resistance Amplitude 0.35 mm IEC/EN 60068-2-6 frequency 10 ... 55 Hz

0 / 050 / 04

Climate resistance: Wire connections

Load terminals: Box terminals with self-lifting

wire protection

Captive M4 Pozidriv-terminal screws 0,5 ... 16 mm² solid

0,5 ... 16 mm² mit stranded wire with sleeve

DIN 46228/1

IEC/EN 60068-1

0,5 ... 16 mm² stranded ferruled (isolated)

DIN 46228/4

21 - 6 AWG

Insulation of wires or sleeve length: 12 mm - 13 mm 2.5 Nm Mounting torque:

Pluggable terminal blocks with **Control terminals**

cage clamp terminals 0.2 - 2.5 mm² solid 0.2 - 2.5 mm² ferruled

0.2 - 2.5 mm² stranded wire with sleeve

DIN 46228/1

0.2 - 2.5 mm² stranded ferruled (isolated)

26 - 12 AWG

Insulation of wires or sleeve length:

8 mm Weight

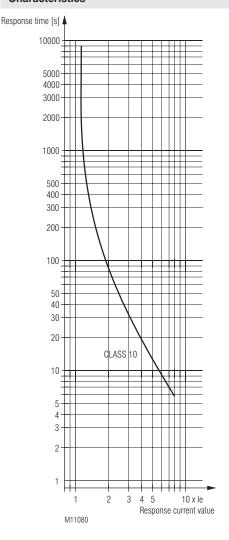
Without DIN rail mounting: 500 g With DIN rail mounting: 600 g

Dimensions

Width x height x depth

Without DIN rail mounting: 67.5 mm x 122.5 mm x 86.5 mm With DIN rail mounting: 67.5 mm x 140 mm x 95.5 mm

Characteristics



Trigger characteristics

Standard Type

PF 9029.11 3 AC 400 V 50 Hz U_H 230 V Hz 25 A

Article number: 0065815

• Load voltage: 3 AC 400 V

• Auxiliary voltage U_H: 230 V

• Nominal operating current I_e: 25 A

• Setting range I_e: 5 A ... 25 A

• Width: 67.5 mm

PF 9029.11 3 AC 400 V 50 Hz U_H 230 V Hz 36 A

Article number: 0067298

• Load voltage: 3 AC 400 V

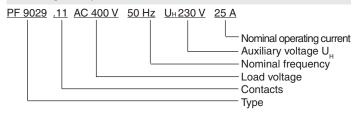
• Auxiliary voltage U_H: 230 V

• Nominal operating current I_e: 36 A

• Setting range I_e: 10 A ... 36 A

• Width: 67.5 mm

Ordering Example



Accessories

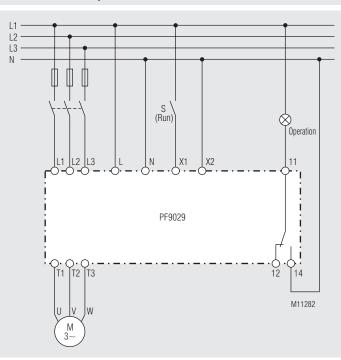
The devices can be mounted on DIN-rail according to IEC/EN 60715 with a fixing plate.

Type: KX4840-20 Article number: 0066204

Operation

- 1. Connect unit as shown in wiring example
- 2. Adjust Potentiometer setting "le" to nominal motor current.

Connection Example



Safety notes

Info

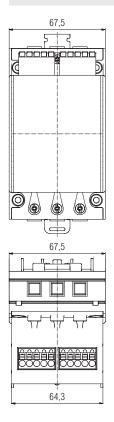
Installation Error!

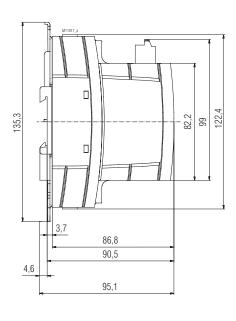
- For engine control units, the minimum loads indicated in the data sheet must be observed.
- The use of capacitive loads can lead to the destruction of switching components of the motor control unit. Do not operate capacitive loads on the motor control unit.

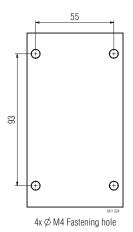


Although the motor is at standstill, it is not galvanically separated from the mains.

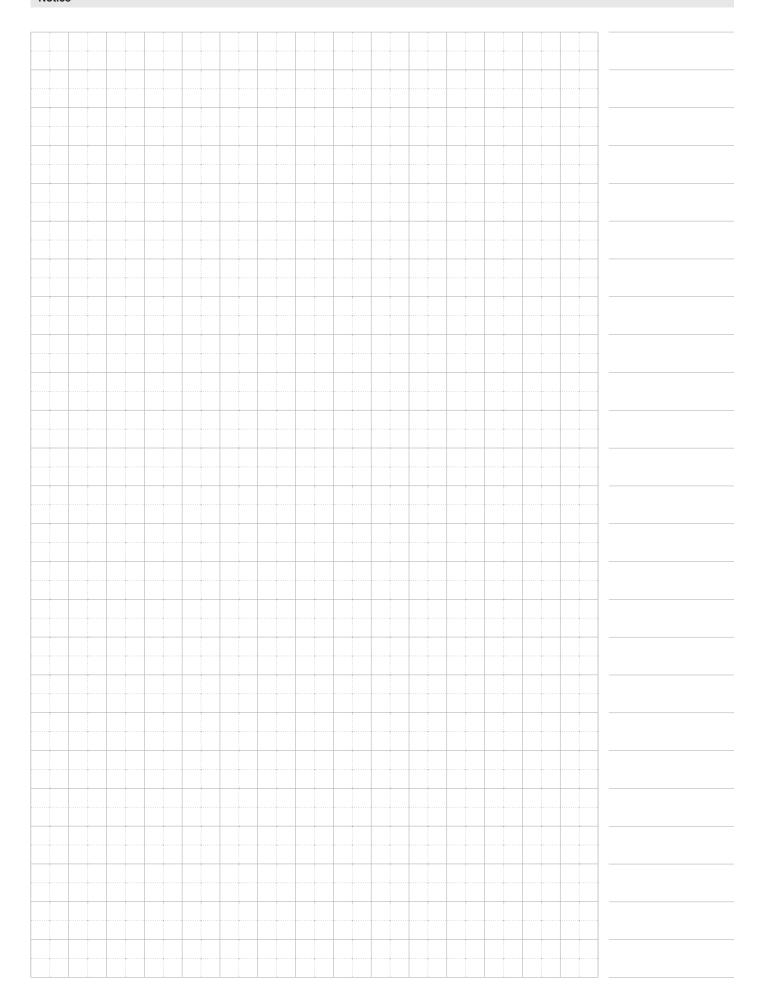
Dimensions







Drilling pattern



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